## STUDY ON TOPO-GEODEZIC WORKS FOR THE REHABILITATION OF THE TRAMLINE IN THE FORD-CRAIOVA AREA

CĂLINA A., CĂLINA JENICA\*, BĂDESCU G., MILUȚ M., IONICĂ C.E., VANGU M. \*Author to whom all correspondence should be addressed: e-mail: jeni\_calina@yahoo.com

Keywords: topo-geodesic elevations, GPS, total station, rehabilitation, situation plan.

## ABSTRACT

The present paper addresses a very complex and difficult research topic, but of great current importance and wide applicability in practice. We affirm this because it is very well known that the road and rail infrastructure 30 years after the revolution is in a very precarious state, we can say very sad, because its rehabilitation and modernization has been done at a very slow pace. Therefore, the working team considered that approaching such a topic of great interest, is beneficial first of all for the practice, since the volume of works of such nature must increase considerably in the future and not lastly it is very valuable from the academic and scientific point of view. In order to solve the thematic approach, the working team used the latest and topographic devices and programs for processing the measured data, which allowed to obtain relevant and very correct results. The working methodology was perfectly adapted to the objective pursued, the situation existing on the ground and the precision imposed by the beneficiary, an aspect that led to obtaining a high execution efficiency of the works, but also to a high economic efficiency, because the time of execution, the volume of works and the number of personnel was greatly reduced.

#### INTRODUCTION

As it is known, the Ministry of Development, Public Works and Housing (MLPTL) technically, economically and coordinates the specialized legally cadastre works of the railways. The approval of the annual specialized cadastre programs of the railways is carried out by the General Direction of the real estate cadastre and the management of the localities within the MLPTL on the basis of the foundation note signed by the railway management of the units (Calinovici I., 2009). In accordance with the obligation regarding the integration of the specialized cadastre into the general cadastre, all the procedures of the railway cadastre must comply with the provisions of the Cadastre Law and the real estate advertising no. 7/1996. with the subsequent modifications, the technical norms and regulations elaborated by ANCPI (Alipour, H. et al, 2019).

The materialization of the points of the geodetic support and survey is made by concrete landmarks, according to the standard types provided in the Order of the Minister of Public Administration no. 534/2001 regarding the approval of the Technical Norms for the introduction of the general cadastre, or other types of landmarks approved by ANCPI, as the case may be. The geodetic lifting networks are created in order to ensure the number of points necessary for topographic and cadastral measurements of detail (Badescu, G. et al, 2018). The density of a geodetic lifting network is determined in relation to the surface on which the works are being carried out and for their purpose and is 1 point/km in the area of the plains, 1 point/2 km in hilly areas, 1 point/5km in mountain areas.

Regardless of the instruments and the technical procedures used to perform the measurements, the geodetic lifting network is compensated as a network constrained on the points of the support and thickening networks (Braun, J. et al., 2018). The standard deviation for determining a point should not exceed: ± 10 cm in the interior and in the extra-

## PURPOSE AND METHOD OF WORK

The purpose of the work was to determine precisely the characteristic points of the studied tram line section, from Craiova locality, Dolj county, from the Ford factory area, for the purpose of rehabilitation. The need to rehabilitate this section of tram line, 1.66 km long, arose due to the deterioration of the rails, joints and crosspieces on which the rails are mounted, for which the traffic of the trams was hampered towards and from some of the economic points interest of Craiova, with a large number of employees using public transport, such as the Ford Factory.

The final purpose of the measurements is the drafting of the topographic situation plans, which consists in representing the topographic points with the elements by which they are determined: poles of the high voltage line responsible for supplying the trams, poles of the air electrical network, the railway, the gutters, the road footprint, the road axis. , boundaries of neighboring properties, poured concrete slabs and other elements encountered on the railway section route.

In order to be drafted in the best conditions all these plans were divided into 10 x 10 cm squares, unique and topography. obligatory in the The resulting grid is attached to the rectangular coordinate system, with the xaxis on the abscissa and the y-axis on the ordinate. Further the design is executed according to the design theme and includes: the technical-economic study of field foundation: research: studies: surveys; existing projects. Using this documentation the technique prior to the design, the development of the project is usually done in two phases: a. The urban area  $\pm$  20 cm in the plain areas;  $\pm$  30 cm in hilly areas,  $\pm$  50 cm in mountainous areas (Calinovici I., and Călina Jenica, 2008).

technical-economic study S.T.E .; b. the execution project P.E.

From the point of view of the research methodology it is known that the topo-cadastral documentation of the cadastral of the railways is drawn up and handed over to the beneficiary and to the OCPI. This should include the following: the approval to start the works, issued by OCPI or ANCPI; the theme of the work; technical report; minutes of handing over all the objectives, accompanied by the corresponding sketches, signed by the representatives of the beneficiary and the executor; the inventory of coordinates of the radiated points: inventory of coordinates and sketches of the support and lifting network; the topographic descriptions of the support and lifting network points; calculating and compensating the coordinates of the points in the support and lifting network; the digital cadastral plan; the delimitation file; the file of the technical verification of the work; the final reception report.

## **RESULTS AND DISCUSSIONS**

In order to be able to achieve the desires proposed in the work, the topographic specialists correctly identified and positioned the route along the tram line, proposed for the rehabilitation, which starts from the intersection of Decebal Boulevard with the E70 road, where it leaves the motorway part, ending at the tram return area, immediately after the Ford Craiova factory (figure. 1).

The topo-geodesic works consisted first in the thorough study of the land in the area, in the execution of the topographic works, the development of the geodesic base and the location on the map of the alignments. The peculiarity of the topo-geodesic works carried out for the purpose of the construction is that they precede and accompany all the stages of the construction, in the broad sense of the word. Preliminary design studies start on maps, within field studies, the topographic works occupying an important part, ensuring the "bringing" in analogue and digital format to the designer level all the necessary information, and based on them he can study the variants regarding the location of the works construction and choose the optimal solution. This project provides the order of execution of the topographic works of tracing, necessary the equipment, the method of field application of angles, lengths, and point dimensions, the way of marking and signaling on the ground the control points and the tracing terms works, the and documents required. The actual execution of the topographic survey consisted of the movement on the ground, where the points to be raised were established and

materialized by metallic picks, were signaled with orange paint. All detail and breaking points were determined using the polar coordinates method. The next execution precedes stage of its application in the field and the detailed tracing of the rehabilitation works of the tram line. Also during the execution of the constructions. the topographic works have a significant role and become indispensable on the construction sites.

The topographic works for the execution of the constructions consists in determining the topographic elements necessary for the tracing on the field of the construction projects, an operation called "the topographic preparation of the execution projects". As a result of the topographic preparation, the characteristic points of the projected construction to be drawn on the ground are obtained, the X, Y and Z coordinates.

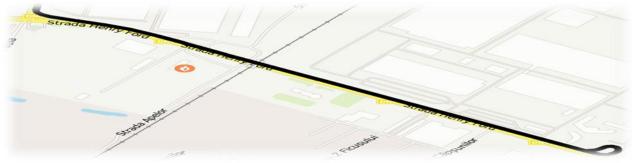


Figure 1. The tram line route

The following steps were taken along the route of the work at the station points: centering of the device, it is specified that if the operation of fitting the device was not performed correctly, it will give an error message and will not record any measurements. After placing the device in the station, the GPS antenna is screwed on, the controller is switched on, then all the data regarding the present location will be set and stored, in the way of determining points: STATIC - 6 points. The stationary time for Static determination of points 1308, 2737, 1448, 1, 2 and 3 was 30 minutes for each station point, compared to the following permanent fixed GNSS stations: CRAI (Craiova) and SLTN (Slatina). The

Controller is started by pressing the ON button and the main menu appears on the display, the operator being able to choose, depending on the purpose of the work, the desired submenus, programs or subprograms.

The first program of the main menu, which is launched at the beginning of the work, requests information about the work to be performed, the operator enters in turn data regarding: name of the work, operator name, type of instrument; the date and time of the beginning of the work and the height of the device, this program being called every time at the beginning of a new measuring session; By launching a special correction program, the operator checks and sets certain parameters such as: index error, horizontal collimation error, date and time. All of these are saved in JOBS, which are similar to directories - jobs contain data measured on each session and can be individually managed, displayed, edited or deleted separately.

All the data that is recorded after the job definition is stored in this directory, and the date and time are automatically entered by the system and cannot be changed - it is validated with the OK key. By using the values recorded in the internal memory, the user of the device is protected from the possibility of entering the data incorrectly. Within the programs used both points with are known coordinates points measured and statically 1308, 2737, 1448, 1, 2 and 3. For each determined point RTK can be entered an identification code, and these codes are useful in the development of the situation plans.

Topo-geodesic operations consist of the use of the 1970 Stereographic

projection system, local quota system, GNSS systems, that is, two Trimble R8S GPS devices and the Trimble S6 total station. For calculating the ETRS 89 coordinates, we used the files in RINEX format (Sui D., 2014), with recordings at 1 second, superimposed on the stationary times with the data collected in the field, from the permanent GNSS fixed stations: CRAI (Craiova) and SLTN (Slatina).

The processing of GNSS data was done with the help of the specialized software Magnet Field. For the calculation points. of determined the the observations from the virtual station RO VRS 3.1.GG (GPS & GLONASS) were used. Subsequent transformation of the new points determined from the ETRS 89 projection system into the STEREOGRAPHIC 1970 projection system was done using the program imposed by A.N.C.P.I. TransDat RO var. 4.04. (Table 1.).

Table 1

| Point no. | NORTH (B)        | EAST (L)         | Z       |
|-----------|------------------|------------------|---------|
|           |                  |                  | (m)     |
| 1308      | 44°17'57.26510"N | 23°49'56.13995"E | 151.663 |
| 2737      | 44°17'57.63585"N | 23°49'54.22084"E | 151.303 |
| 1448      | 44°17'58.27450"N | 23°49'55.50892"E | 152.272 |
| 1         | 44°17'32.75674"N | 23°50'48.99551"E | 156.777 |
|           | 44°17'31.44698"N | 23°50'52.59189"E | 156.677 |
| 3         | 44°17'31.52394"N | 23°50'52.58630"E | 156.667 |

## The coordinates of the stationed points in ETRS 89 system

TransDatRO - Transformari de coordonate formare Puncte Romania Transformare Puncte Bucuresti Window Help

| Intrare: (B, L, h)         | lesire: (x, y, H_MN)  |
|----------------------------|-----------------------|
| B 44 * 17 ' 57 . 26510 " N | x (Nord) 311724.744 m |
| L 23 ° 49 ' 56 . 22084 " E | y(Est) 406938.683 m   |
| h 151.663 m                | H_MN 111.170 m        |

Figure 2. Transforming the coordinates of the ETRS 89 system into Stereo 70

In order to determine the support network, a supported routing was carried out at both ends starting from station point 1308 oriented on 1488 and verified on 2737, through stations 1204, 940, 809, 692, 527, 171 and closed on station point 1, oriented on point 2 and verified on point 3. From the station points 1308, 1204, 940, 809, 692, 527, 171, 189, 125 and 1 the necessary measurements were made for the preparation of this documentation (figure 3).



#### Figure 3. The route of supported traverse

The compensation method used was the method of weighted indirect observations, which implies the block compensation for the coordinate differences ( $\Delta X$ ,  $\Delta Y$  and  $\Delta Z$ ), resulting from GPS data measurements and processing. Stations 1308, 2737, 1448, 1, 2 and 3 were also determined GNSS (GPS), using the static method according to Decision no. 1 of 2010.

At the actual accomplishment of the lifting method, an initial recognition was

made in the field of the route and the choice of the location of the points to be stationed with the GPS equipment, taking into account the regulations in force. The measurement operations met the following criteria (Salagean, T., et al, 2011): - there are no obstacles obstructing the horizon; - there should be no reflecting surfaces near the antennas, as these can lead to the multipath effect; be easily accessible; - be protected from destruction.

Table 2

| Număr | Coordonate Ste | reografice 1970 | Număr | Coordonate Ste | reografice 1970 |
|-------|----------------|-----------------|-------|----------------|-----------------|
| punct | X(m) Y(m)      |                 | punct | X(m)           | Y(m)            |
| 1308  | 311724.770     | 406936.890      | 1     | 310951.491     | 408097.710      |
| 2737  | 311736.829     | 406894.516      | 2     | 310909.928     | 408176.861      |
| 1448  | 311756.127     | 406923.352      | 3     | 310912.305     | 408176.771      |

### The coordinates of the support points located in the Stereo '70 system

On the field there was also a thickening network marked with metal bolts that rests on the previously constructed support network. The points of this network are located on the route of the studied tram section, at convenient distances to perform topographic surveys with high accuracy.

An important step in solving this traverse is the calculation of the orientation of the station points and the compensation of all the measured directions, according to tables 3, and 4.

In making it, the same norms regarding stability, conservation,

accessibility and efficiency for surveying are taken into account. For the points of the lifting network, the method of planimetric routing supported at ends on known coordinate points (table 5.) was used, as well as the method of geometric leveling. The device used to perform the planimetric traverse is the total station following Trimble S6 with the characteristics: - the angle measurement accuracy: 2 seconds; - accuracy of measuring distances: 2mm + 2ppm; range of measurement of distances with a single prism: 2500-5500m (Radu, O. et al, 2017).

In each traverse station, the directions were measured by the horizon tour method. The distances were determined by electronic measurements back and forth. The calculation of the traverse was done on a separate section, closing on a base of the support network

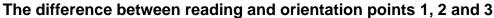
(tab. 5). The network processing was performed with specialized software (Raza, H., et al, 2017). The closures obtained on this section fall within the tolerances imposed by the norms in force, as can be seen from the presented calculations (table 6.).

Table 3

### The difference between reading and orientation points 1308, 1488 and 2737

| No. | Station point   | Differences (g),<br>(col. 3 – col. 4) |          |            |           |  |  |  |  |  |
|-----|---|---------------------------------------|----------|------------|-----------|--|--|--|--|--|
| 0   | 1   | 5                                     |          |            |           |  |  |  |  |  |
| 1   | 1308  | -149.7848                             |          |            |           |  |  |  |  |  |
| 2   | 1308  | -149.7878                             |          |            |           |  |  |  |  |  |
|     | RESULTS OF THE CALCULATION AND DIFFERENCE BETWEEN<br>THE TARGETED POINTS   0.0030     * A correction is applied on both directions of 15 seconds   0.0030 |                                       |          |            |           |  |  |  |  |  |
| 7.0 |   | Directions read off                   |          |            |           |  |  |  |  |  |
| 1   | 1308  | 1488 (-0.0015)                        | 147.3430 | 297.1293   | -149.7863 |  |  |  |  |  |
| 2   | 1308  | 2737 (+0.0015)                        | 167.8643 | 317.6506   | -149.7863 |  |  |  |  |  |
| RES | SULTS OF THE  | CALCULATION A<br>THE TARGETED         |          | CE BETWEEN | 0.0000    |  |  |  |  |  |

Table 4



| No.                        | Station<br>point  | Target p   | oint  | Reading   | (g)  | Orienta   | tion (g)   |   | erences (g)<br>. 3 – col. 4)            |
|----------------------------|---|--|---|---|--|-----------|--|---|---|
| 0                          | 1   | 2  |   | 3   |  | 4         | ŀ  |   | 5                                       |
| 1                          | 1   | 2  |   | 381.018   | 38   | 130.7     | 7827   | 2   | 50.2361                                 |
| 2                          | 1   | 3  |   | 379.528   | 35   | 129.2     | 2944   | 2   | 50.2341                                 |
| RESL                       | JLTS OF THE   | CALCULA  | TION A  | ND DIFF   | EREN   | VCE BET   | WEEN   |   |   |
|                            |   | THE TAR  | GETED   | POINTS  | 5  |           |  |   | 0.0020                                  |
| * A co                     | prrection is ap   | plied on bot   | th direct   | tions of 1  | 0 sec  | onds      |  |   |   |
|                            |   | Directio   | ons read  | d offset,   | point  | s 1, 2 ar | nd 3   |   |   |
| 1                          | 1   | 2 (-0.00   | )10)  | 381.017   | 78   | 130.7     | 7827   | 2   | 50.2351                                 |
| 2                          | 1   | 3 (+0.00   | 010)  | 379.529   | 95   | 129.2     | 2944   | 2   | 50.2351                                 |
| RESL                       | JLTS OF THE   | CALCULA  | TION A  | ND DIFF   | EREN   | NCE BET   | WEEN   |   |   |
| THE TARGETED POINTS 0.0000 |   |  |   |   |  |           |  |   |   |
|                            |   |  | GETED   | FOINTS  | J  |           |  |   |   |
|                            | ru ADACAD - DRUM FINA<br>View Procedee topo   |  | GETED   | POINTS  |  |           | _  |   |   |
|                            |   | LA.tpo   |   |   | ,<br>  |           |  |   |   |
| iect Edit                  | View Procedee topo  | <b>LA.tpo</b><br>Ajutor  |   |   | _  |           | E I  |   |   |
| iect Edit                  | View Procedee topo   ※ Pa   ※ Pa  | <b>LA.tpo</b><br>Ajutor  |   |   |  |           | ×  |   | 00                                      |
| iect Edit                  | View Procedee topo  | LA.tpo<br>Ajutor<br><b>P A C P</b><br><b>C</b><br>i directii orizontale in<br>secunde foci   | * 0   | 1486  |  | ,692,527, | Punct de 2<br>sosire 2<br>unct sosire 1                                      |   | Calculeaza                              |
| iect Edit                  | View Procedec topo  | IALTPO<br>Jutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor<br>Valutor | Punct de<br>vienatare la<br>plecare 11<br>unct plecare 11<br>Distanta red | 1498 TF<br>308 T  | RASEU<br>204 940,809<br>71<br>dy   | 1692.527. | Punct de<br>orienatare la<br>sosire<br>Punct sosire 1<br>9<br>406936.890     | dh  | Calculeaza                              |
|                            | View Procedec topo<br>X Pa Call Call Call Call Call Call Call C   | Itoximalia de cilire a<br>i directi orizontale in<br>secunde (cc)<br>0.01<br>Pu<br>net vizat Orientare<br>18 227 1293<br>14 126 5969<br>-0.0046<br>126 6962  | Punct de<br>piecare [1]<br>unct piecare [13]<br>Distanta red<br>207.577   | 1499 1 [1]<br>308<br>1usa dx<br>-85.394<br>-0.030<br>-85.424  | RASEU<br>204,940,809<br>71<br>189,188<br>0.004<br>189,192                            | .682.527. | Punct de<br>orienatare la<br>2001 Punct sosire 1<br>406936.890<br>407126.082 | <b>dh</b><br>1.622<br>-0.007<br>1.615             | <u>C</u> alculeaza<br>111.17<br>112.786 |
|                            | View     Procedec topo       X     Pa     Pa       X     Pa     Pa       FINALA.tpo:1     RUM FINALA.tpo:2       Tip     C     Stereo       C     Cocal     Ar       Dummie     Pancet statie     Pau       1     1306     144       2     1306     124       3     1204     944       6     1204     944 | Control  | Punct de<br>vienatare la<br>plecare 11<br>unct plecare 11<br>Distanta red | 1499<br>308<br>1499<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119<br>119 | RASEU<br>204, 940, 809<br>71<br>189, 198<br>0, 004<br>189, 192<br>156, 228<br>0, 004 | 1692.527. | Punct de<br>orienatare la<br>sosire<br>Punct sosire 1<br>9<br>406936.890     | dh<br>1.622<br>-0.007<br>1.615<br>0.427<br>-0.007 | Calculeaza                              |
|                            | View Procedec topo  | LA.tpo<br>Ajutor<br>Vointella de cilies a<br>i difecti orcontale in<br>secunde (cc)<br>0.01<br>Pr<br>126.9963<br>144.2469<br>-0.0091<br>144.2439<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091<br>-0.0091    | Punct de<br>piecare [1]<br>unct piecare [13]<br>Distanta red<br>207.577   | 1499 • • • • • • • • • • • • • • • • • •  | ASEU<br>204,940,809<br>71<br>189,188<br>0,004<br>189,192<br>156,228                  | .682.527. | Punct de<br>orienatare la<br>2001 Punct sosire 1<br>406936.890<br>407126.082 | dh<br>1.622<br>-0.007<br>1.615<br>0.427           | <u>C</u> alculeaza<br>111.17<br>112.786 |

Figure 7. Calculation and definition of the traverse using the TOPO CALC program

Table 5

Calculation of the supported traverse

| Start point   | 1308 | Orientation to departure $\Theta$ | 1488 |
|---------------|------|-----------------------------------|------|
| Arrival point | 1    | Arrival orientation $\Theta$      | 2    |

| Traverse route 1308,1204, 940, 809, 692, 527, 171, 1 |
|--|
|--|

| Station point | Target<br>point | Orientation<br>$\Theta$ | Reduced distance | ΔΧ       | ΔΥ      | X          | Y          | ΔZ     | Z       |
|---------------|-----------------|-------------------------|------------------|----------|---------|------------|------------|--------|---------|
| 1308          | 1488            | 297.1293                |                  |          |         | 311724.770 | 406936.890 |        | 111.170 |
| 1308          | 1204            | 126.9969                | 207.577          | -85.394  | 189.188 | 311639.346 | 407126.082 | 1.622  | 112.785 |
|               |                 | -0.0046                 |                  | -0.03    | 0.004   |            |            | -0.007 |         |
|               |                 | 126.9923                |                  | -85.424  | 189.192 |            |            | 1.615  |         |
| 1204          | 940             | 144.2469                | 203.391          | -130.229 | 156.228 | 311509.088 | 407282.313 | 0.427  | 113.205 |
|               |                 | -0.0091                 |                  | -0.029   | 0.004   |            |            | -0.007 |         |
|               |                 | 144.2378                |                  | -130.258 | 156.232 |            |            | 0.420  |         |
| 940           | 809             | 139.6353                | 273.088          | -159.2   | 221.881 | 311349.849 | 407504.199 | 1.566  | 114.762 |
|               |                 | -0.0137                 |                  | -0.039   | 0.005   |            |            | -0.009 |         |
|               |                 | 139.6216                |                  | -159.239 | 221.886 |            |            | 1.557  |         |
| 809           | 692             | 128.3197                | 153.527          | -66.028  | 138.61  | 311283.799 | 407642.812 | 2.927  | 117.684 |
|               |                 | -0.0182                 |                  | -0.022   | 0.003   |            |            | -0.005 |         |
|               |                 | 128.3015                |                  | -66.05   | 138.613 |            |            | 2.922  |         |
| 692           | 527             | 139.9365                | 170.345          | -99.938  | 137.946 | 311183.84  | 407780.76  | -0.417 | 117.261 |
|               |                 | -0.0228                 |                  | -0.024   | 0.003   |            |            | -0.006 |         |
|               |                 | 139.9137                |                  | -99.962  | 137.94  |            |            | -0.423 |         |
| 527           | 171             | 141.6205                | 146.747          | -89.198  | 116.524 | 311094.62  | 407897.29  | -0.410 | 116.846 |
|               |                 | -0.0274                 |                  | -0.021   | 0.003   |            |            | -0.005 |         |
|               |                 | 141.5931                |                  | -89.219  | 116.527 |            |            | -0.415 |         |
| 171           | 1               | 139.5047                | 246.258          | -143.092 | 200.419 | 310951.49  | 408097.71  | -0.559 | 116.279 |
|               |                 | -0.0319                 |                  | -0.035   | 0.004   |            |            | -0.008 |         |
|               |                 | 139.4728                |                  | -143.127 | 200.423 |            |            | 0.567  |         |
| 1             | 2               | 130.8083                |                  |          |         |            |            |        |         |
|               |                 | -0.0365                 |                  |          |         |            |            |        |         |
|               |                 | 120 77 19               |                  |          |         |            |            |        |         |

130.7718

Or

Table 6

| Erre                 | or calculati | on and tolerance      |            |
|----------------------|--------------|-----------------------|------------|
| Azimuthal error      | -0.0365      | Coordonates error     | 0.2015     |
| rientation tolerance | 0.0566       | Coordinates tolerance | 0.3925     |
| kx                   | -0.00014     | kz                    | -0.0000328 |
| ky                   | 0.000017     | Er. z                 | -0.046     |
| Dif. x:              | -0.2000      | Tol. z                | 0.2367     |

0.0243

The detail points were raised by the polar coordinates method, using as station points 1308, 1204, 940, 809, 692, 527, 171, 173, 189, 125 and 1, from

Dif. y:

where were targeted the detail and outline points necessary for the preparation of the situation plan (tab.7). The coordinates of the points were calculated quickly and accurately with the help of the specialized program TopoCalc (Şmuleac, A., et al, 2017) and passed to table 7, which is simplified.

The constructive elements of the tram line were rendered by the profile method, being prepared for the surveyied section longitudinal and transverse profiles, perpendicular to the direction of the tram lines, in all the characteristic points, according to the specification. The length of the studied tram line section proposed for rehabilitation is 1661 m and is rendered by longitudinal profile, performed at the stairs imposed in the specification Sc. H. 1: 100 and Sc. L. 1: 1000 (figure 8). At the request of the beneficiary, the longitudinal profile was made from all the joints and braking points of the route, on one of the four railway tracks.

Table 7

|          | Target |           | Orientation | Inclined | Zenith   | Reduced  |            |         |            |            |        |         |
|----------|--------|-----------|-------------|----------|----------|----------|------------|---------|------------|------------|--------|---------|
| Station  | point  | Direction | Θ           | distance | angles   | distance | $\Delta X$ | ΔΥ      | Х          | Y          | ΔZ     | Z       |
| 1        |        |           |             |          |          |          |            |         | 310951.491 | 408097.710 |        | 116.279 |
| Acord    | 2      | 381.0178  | 130.7831    | 89.400   | 100.1048 | 89.400   | -41.563    | 79.151  | 310909.928 | 408176.861 | -0.104 | 116.175 |
| 149.7653 | 3      | 379.5292  | 129.2945    | 88.240   | 100.1072 | 88.240   | -39.186    | 79.061  | 310912.305 | 408176.771 | -0.106 | 116.173 |
|          | 4      | 372.7570  | 122.5223    | 48.256   | 100.2130 | 48.256   | -16.718    | 45.267  | 310934.773 | 408142.977 | -0.118 | 116.161 |
|          | 5      | 205.1114  | 354.8767    | 14.977   | 97.5044  | 14.965   | 11.361     | -9.741  | 310962.852 | 408087.969 | 0.630  | 116.909 |
|          |        |           |             |          |          |          |            |         |            |            |        |         |
| 527      |        |           |             |          |          |          |            |         | 311183.837 | 407780.760 |        | 117.261 |
| Acord    | 563    | 397.7594  | 147.5303    | 51.504   | 100.7132 | 51.501   | -34.977    | 37.802  | 311148.860 | 407818.562 | -0.522 | 116.739 |
| 149.7709 | 564    | 393.6426  | 143.4135    | 51.294   | 100.6334 | 51.291   | -32.329    | 39.820  | 311151.508 | 407820.580 | -0.455 | 116.806 |
|          | 565    | 392.3516  | 142.1225    | 51.117   | 100.6882 | 51.114   | -31.406    | 40.328  | 311152.431 | 407821.088 | -0.498 | 116.763 |
|          | 566    | 390.4688  | 140.2397    | 51.136   | 100.6934 | 51.133   | -30.211    | 41.254  | 311153.626 | 407822.014 | -0.502 | 116.759 |
| •••      |        |           |             |          |          |          |            |         |            |            |        |         |
| 1308     |        |           |             |          |          |          |            |         | 311724.770 | 406936.890 |        | 111.170 |
| Acord    | 1310   | 377.2088  | 126.9983    | 207.579  | 99.3808  | 207.569  | -85.413    | 189.181 | 311639.357 | 407126.071 | 1.615  | 112.785 |
| 149.7895 | 1311   | 375.1888  | 124.9783    | 114.635  | 100.6536 | 114.629  | -43.831    | 105.918 | 311680.939 | 407042.808 | 0.431  | 111.601 |
|          | 1312   | 374.6204  | 124.4099    | 114.245  | 99.4992  | 114.241  | -42.738    | 105.946 | 311682.032 | 407042.836 | 0.495  | 111.665 |
|          | 1313   | 373.9902  | 123.7797    | 113.530  | 99.5122  | 113.527  | -41.427    | 105.698 | 311683.343 | 407042.588 | 0.466  | 111.636 |

# Calculation of details coordinates

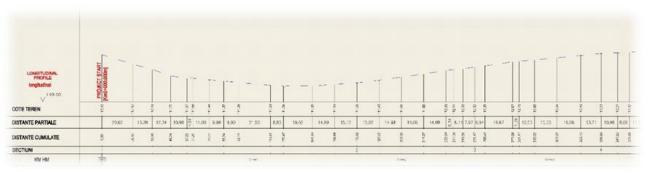


Figure 8. Longitudinal profile scale: H 1: 100 - L 1: 1000

Conclusions In order to reproduce the constructive section of the tram line as accurately as possible, the topographic specialists carried out transverse profiles in all the characteristic points, as follows (fig.9.): Near the high voltage poles between the tram directions; near the joints on the railway lines (the joints are the points where two railings are joined and welded); profiles as often as possible in the tram return area, respectively in the places where the railway line is curved.

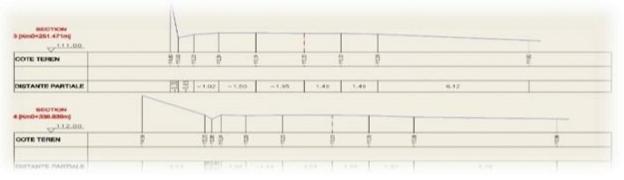


Figure 9. Type of cross-sectional profile made at the characteristic points

The drawing up of these types of profiles is absolutely mandatory in the case of engineering works of this nature, because the following obligatory points must be given: fence (where it exists); quota points; gutter; CF (provided we mark each place on the railway where there are joints, ie the place where the tram tracks are welded); the pillars belonging to the electrical network responsible for the power supply, with the current of the trams; sidewalk; road; axis (Călina, J. et al, 2018).

In order to obtain the complete topographic plan, it was necessary to carry out additional elevations through which the following details were reproduced with great precision and fidelity: the kilometric terminals; hectometric terminals; property limits; fireplaces, sewage; hydrants; electricity poles, internet; tram shelters (stations); annexed buildings of RAT Craiova. To all the above, at the operator's decision, any other details necessary to be included in the situation plan are added, so that they are finally complete and correct (Călina, J. et al, 2014).

The final result of this work was the comprehensive situation plan, consisting of 11 sheets of A1 format, realized on scale 1: 200 (figure10.), stipulated in the specifications, together with the beneficiary of the work.

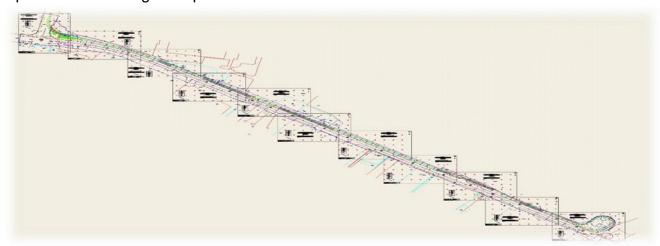


Figure 10. Situation plan realized on scale 1: 200

### CONCLUSIONS

In order to prepare the topographic project, the work team first performed a preliminary study which consisted of land recognition, establishing the route of the secondary network and the number of stations required to raise all the detail points, after which the geodetic network of thinning and lifting was carried out to ensure the density of points necessary to perform all the topo-geodesic works, in the best conditions of quality and precision.

Also, with the drafting of the specifications execution project. the including requirements strictly related to the area occupied by the tram tracks constructed, the beneficiary were subsequently adding the road part of the European road E70, which led to the inclusion in it of all the characteristic elements. presented during the paper. While carrying out the work of organizing the site, new requirements appeared, such as the short execution time for the completion of the work, which could be achieved only by using high-performance, fast and high-precision work equipment such as GPS and the total station.

A relevant and very specific aspect only for such works is the degree of difficulty of the topographic works, which were greatly hampered by the intense traffic on the road associated with the studied tram section, which led to the need to take security measures in the type of work, to avoid the accident, were used transmitting-reception stations and reflective equipment.

The final technical documentation drawn up after the execution of the geodetic networks of support, thickening subject to the reception and lifting operations includes: technical the memory, (including the general description of the work, working methods, tools used, data processing, the obtained precision, etc.); the diagram of the measurements made; ASCII files, on magnetic media, with the data resulting from the field measurements (name / number of station point, name / number of points. directions measured. target distances measured); topographic description and sketching drawings for points; inventory old and new of including magnetic coordinates on wellsupport. Based on this very documented documentation. in compliance with all legal and precision requirements, the approval and approval of ANCPI was obtained, thus being able to start the execution of the works.

### BIBLIOGRAPHY

1. Alipour, H., Jalalian, A., Honarjoo, N., Tommanian, N. and Sarmadian, F., 2019, Spatial and Temporal Distribution of Dust-Bound Trace Metal Elements Around Kuhdasht Watershed Area in Iran. CLEAN–Soil, Air, Water, p.1900318.

2. Badescu, G., Calina, Jenica, Calina, A., Milut, M., Stan, I., 2018, Use of modern methods of terrestrial laser scanning on preservation of the religious patrimony in Romania, European Journal of Science and Theology, Vol. 14, Issue. 5, pp 201-207

3. **Braun, J., Kremen, T. and Pruska, J.**, 2018, *Micronetwork for Shift Determinations of the New Type Point Stabilization.* In 2018 Baltic Geodetic Congress (BGC Geomatics) (pp. 265-269). IEEE.

4. Călina, J., Călina, A. and Băbucă, N., 2014. Study on the implementation of GIS databases in achieving the general urban plan. In 4th International Multidisciplinary Scientific GeoConference SGEM 2014, Conference Proceedings, Book (Vol. 2, pp. 817-824).

5. Călina, J., Călina, A., Bădescu, G., Vangu, G.M. and Ionică, C.E., 2018. Research on the use of aerial scanning for completing a GIS database. AgroLife Scientific Journal, 7(1), pp.25-32.

6. **Calinovici I., and Călina Jenica**, 2008, *Topography*, Ed., Mirton, Timisoara.

7. **Calinovici, I.**, 2009, Researches concerning the topography of an area of ground with the purpose of its

agroecological reconstruction. In Proceedings. 43rd Croatian and 3rd International Symposium on Agriculture. Opatija. Croatia (Vol. 125, p. 128).

8. Radu, O., Cimpeanu, S.M., Teodorescu, R.I. and Bucur, D., 2017. Technical efficiency of the subsurface drainage on agricultural lands in the Moldova river meadow. Kulshreshtha S. Current Perspective on Irrigation and Drainage. London: IntechOpen, pp.69-81. 9. Raza, H., Park, S.I., Lee, S.S., Tanoli, W.A. and Seo, J., 2017. 3D Earthwork BIM Design Process for a Road Project. Journal of KIBIM, 7(2), pp.8-15. 10. Salagean, T., Dîrja, M., Ortelecan, M., Pop, N., & Deak, J. (2011). 3D Modeling of the USAMV Cluj-Napoca campus using integrated system google earth–sketchup and 3d warehouse. Agricultura, 79(3-4)

11. **Sui D.,** 2014. Opportunities and Impediments for Open GIS. Transactions in GIS, 18 (1), p. 1-24, doi:10.1111/tgis.12075.

12. Şmuleac, A., Popescu, C., Bărliba, L., Ciolac, V., & Herbei, M., 2017. Using the GNSS technology tothicken geodesic network in Secaş, Timiş County, Romania. Research Journal of Agricultural Science, 49(3).